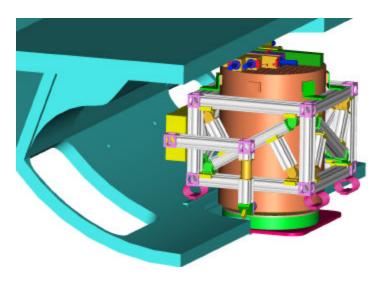
## Raman Airborne Spectroscopic Lidar (RASL)

- •Airborne Raman Lidar under development through IIP1
- •Main measurements:
  - •Water vapor (day, night)
  - •Aerosol scattering, extinction, depolarization (day, night)
  - •Cloud liquid water (night)
- •Laboratory demonstration by the end of IIP 1
- •Technology improvements and flight test proposed to IIP2
- •Replacement of oxygen filter by CO<sub>2</sub> filter permits the profile of CO<sub>2</sub> to be measured

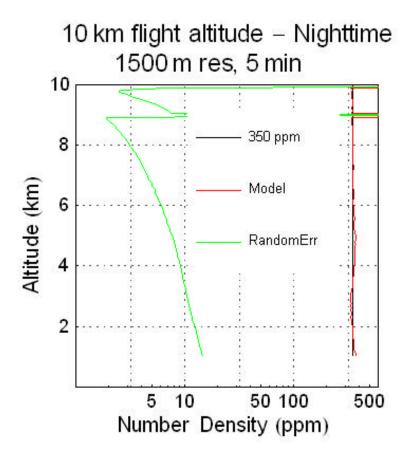


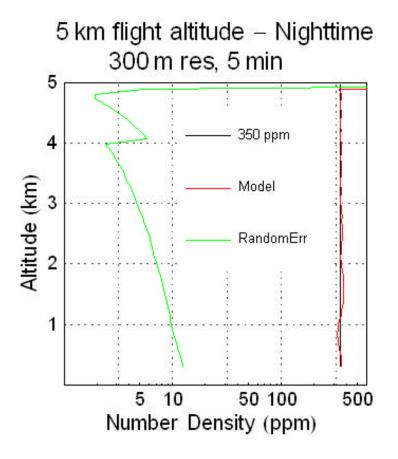
*RASL* in the DC-8 cargo bay

## **RASL Components**

- •Tripled Nd:YAG laser
- •24" athermal telescope
- •7.5 meter range resolution
- •Fiber optics port for additional measurements
- •Designed for DC-8 and P-3 compatibility

## RASL Simulations as CO<sub>2</sub> Profiler





Increased integration time (repeated sampling of an area) could be done to improve precision (e.g. an X or box pattern to study horizontal fluxes through the sides of the box). If using a 15 minute average, divide the errors shown by 1.7 Degraded vertical resolution achieves the same effect.